# ULTLA-LOW-SPEED SYNCHRONOUS MOTORS

The demand for low speed motors for control use is sure to increase with the recent demand for more automated, labor saving machines and facilities. The gears, pulleys, other mechanical speed reduction devices used in the past to obtain low speed involve difficult problems related to life, noise, dimensions, maintenance, etc. Fuji Electric has made considerable progress in the development of an inductor type synchronous motor which provides ultra-low-speed electrically and without any of the above disadvantages.

The motors presently available in this new series are introduced here. Over 1,000 units already in wide use have been highly acclaimed.

#### **Features**

- 1) Ultra-low-speed (60/72 rpm) can be obtained without the use of mechanical speed reduction devices. Consequently, life and maintenance need not be considered.
- 2) Since they are synchronous motors, their speed remains constant and is uneffected by load torque.
- 3) Rush current during starting and reversing is extremely small and is no larger than the operating current
- 4) Starting and stopping times are extremely short  $(10 \sim 50 \text{ ms})$ , thus they are suitable as servomotor.
- 5) Self-starting is possible and they can be freely rotated in any direction.
- 6) Fairly high static hold torque even when unexcited. Moreover, a static hold torque greater than the rated torque can be obtained by DC excitation.
- 7) Motor will not burn up even if continuously locked and can withstand a starting and stopping frequency of 2 times per second.
- 8) Single-phase source can be used.
- 9) Since a symmetrical 2-phase winding with capacitor splitting is used, forward and reverse operation is simple.
- 10) Since they are fully enclosed, little installation space is required.
- 11) Stepping operation at a step angle of 1.8° is possible when a pulse source is used.

# **Applications**

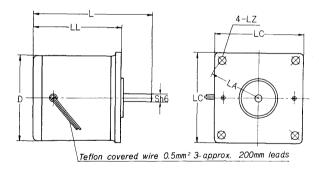
- · Valve/damper operator
- · Positioning of machine tools and other machines
- · Electrode vertical movement device
- · Control/measurement equipment
- · Other ultra-low-speed applications

## Standard Specifications

1.5	3.	7.5	15	45	90				
2.4/2.0	4.8/4.0	12/10	24/20	73/61	146/122				
100									
100±10									
0.1/		0.4/ 0.32	0.7/ 0.55	2.4/1.8	4.5/3.5				
50/60									
60/72									
1.8	6	10	15	30	50				
0.72	1.6	6	9	18	32				
Class F									
Temperature: $-20 \sim +40 \text{C}^{\circ}$ Humidity: 85% less									
	0.1/0.09	2.4/2.0 4.8/4.0  0.1/ 0.09 0.15  1.8 6  0.72 1.6	2.4/2.0 4.8/4.0 12/10  100  0.1/ 0.09 0.13/ 0.01 0.32  50  1.8 6 10  0.72 1.6 6  Cla Temperatur	$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$				

Becomes ¼ this value when indicated by moment of inertia.

### **Exterior Dimensions**



						Unit: mm	
Nominal output (W)	LA	LC	D	L	ĹL	LZ	s
1.5	70 105	60 95	60 88	80 99	60 69	5 6	6.3 9.5
7.5	156	135	119	156	128	10	14
15	156	135	119	203	175	10	14
45	226	200	178	212	174	15	18
90	226	200	178	288	250	15	18

